

Opportunities and barriers in application of stochastic differential equations to agriculture and ecology

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This talk features joint work with many colleagues including:

Chris Pooley (BioSS), Stephen Bishop (Roslin Inst.), Nikos Alexandridis (Lund), Sonia Mitchell (BioSS), Lucio Marcello (BioSS) Lesley Smith (SRUC), Mike Hutchings (SRUC), Alex Corbishley (Edinburgh), Andrea Doeschl-Wilson (Edinburgh), Kokouvi Gamado (BioSS), Thibud Porphyre (Lyon), Stephen Catterall (BioSS), Siu Yin 'Max' Lau (Emory), George Streftaris (Heriot-Watt), Gavin Gibson (Heriot-Watt), Martin Knight (BioSS), Piran White (York) and Ross Davidson (SRUC).



Aims –

Review our
applications in
agriculture and
ecology

Highlight challenges &
opportunities for
STOCHASTICA

Population modelling

Demographic stochasticity and realistic noise terms

Modelling heterogeneity

The need to represent heterogeneity

Spatial models

Spatial dynamics and spread

Individual and agent-based models

Individual behaviours shape system dynamics

Assessing model fit to data

Challenges for modelling fitting
Inference for spatial models
Assessing model fit

Comment –

**To consider in terms
of identifying
challenges &
opportunities for
STOCHASTICA**

**In our applications typically make more use of
discrete state-space stochastic processes**

Why is this?

Biological realism?

Lack of appropriate results?

Lack of suitable tools?

Lack of awareness of suitable tools and results?

**Perceived difficulty in applying tools and results
that are available?**

Background concepts

Discrete state stochastic processes

**Bayesian inference for latent stochastic
processes**

Discrete State Space Markov Processes

DCTMPs

- N compartments, integer populations $n(t)$
- E event types, each alters state via Q
- Rates $r(t)$ depend only on current state
- Simulated via Doob–Gillespie algorithm

Section 2 — General Framework & SIS Illustration

General DCTMP (Eq. 2.1)

$$n_c = n_c + Q_{ce}$$

State vector $n(t)$

N compartments, each holding an integer population count.
Space of configs is discrete.

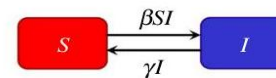
Transition matrix Q

Fixed matrix. row e=event gives the change to each compartment when event type e fires.

Rate vector $r(\theta, n)$

Average rate of each event.
Depends on current state $n(t)$ and parameters θ only (Markov property).

SIS Example (Eq. 2.2)



n $(S, I)^T$ — susceptible & infected counts

θ (β, γ) — infection & recovery rates

r $(\beta SI, \gamma I)$ — event rates

Q $\begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$ — infect: $S \downarrow, I \uparrow$
recovery: $I \downarrow, S \uparrow$

Markov property: rates r depend only on current state $n(t)$, not history. Enables exact simulation via Doob–Gillespie and analytical expressions for event-sequence probability.

Bayesian Inference Framework

Combining Parameters,
Event Sequences & Data

Posterior:

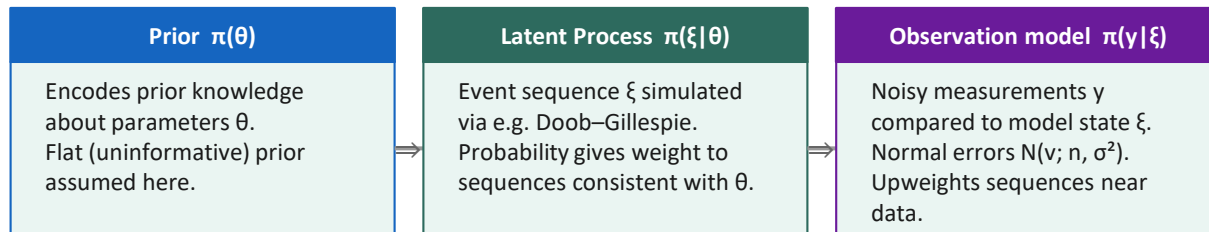
$$\pi(\theta, \xi | y) \propto \pi(y|\xi) \cdot \pi(\xi|\theta) \cdot \pi(\theta)$$

$\pi(y|\xi)$ Observation model

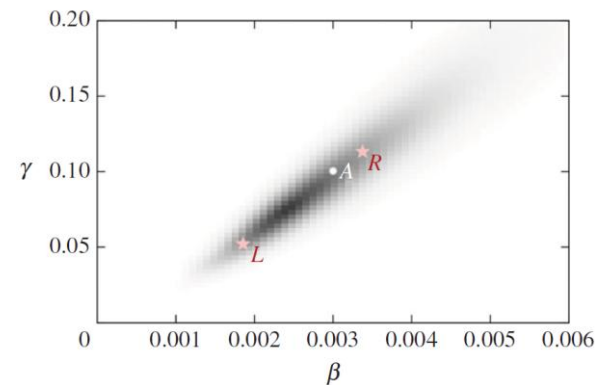
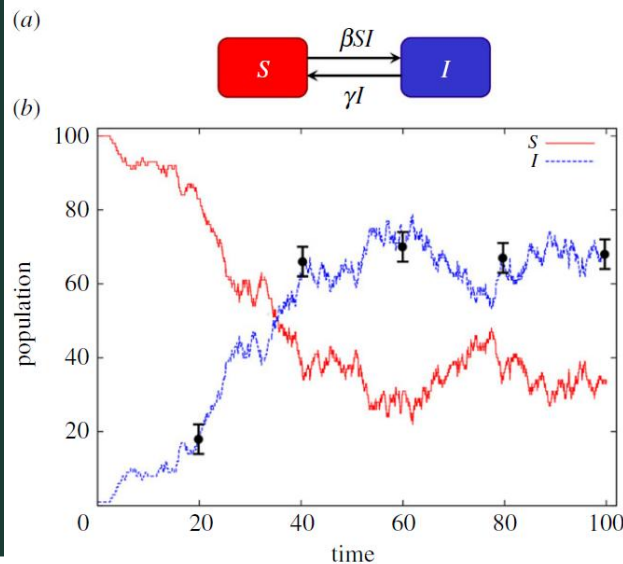
$\pi(\xi|\theta)$ Latent process likelihood

$\pi(\theta)$ Prior on parameters

Bayesian Framework for stochastic process models



Posterior $\pi(\theta, \xi | y)$ — probability distribution over parameters and event sequences, given the data



Key issue: efficient sampling of joint space of parameters and events

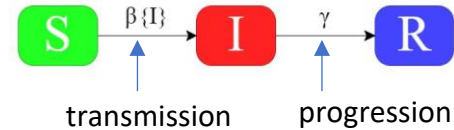
Computational stats and epi-models

epi-models: disease transmission and progression

data: real world data provides (multiple) part(s) of the picture e.g. case reports when symptoms show

Bayesian approach: allows use of prior knowledge

computational statistics: provide practical way to combine the above to estimate uncertainties involved and predict the unseen e.g. transmission and progression events



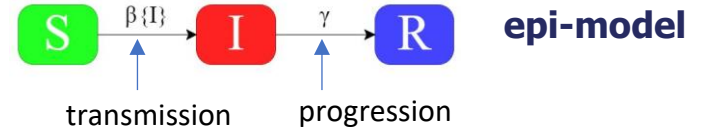
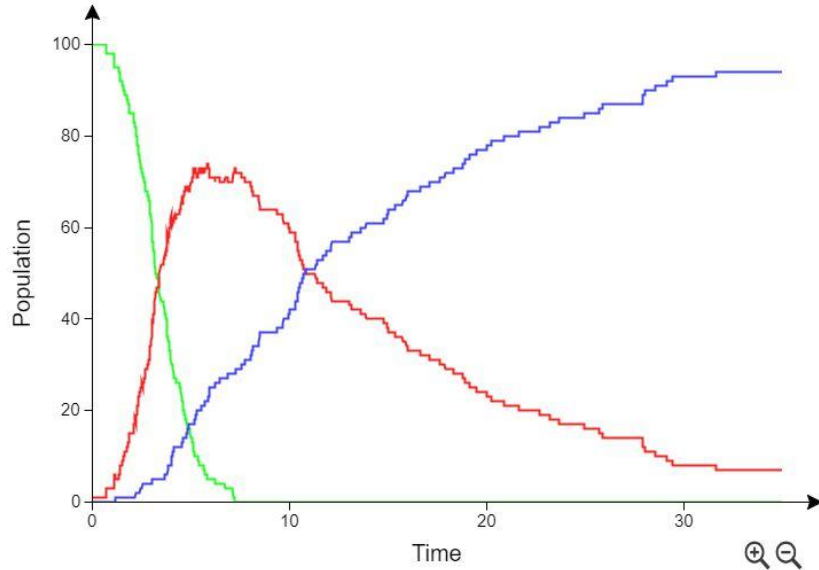
We talk about *inference* because data is incomplete and noisy and do doesn't provide a complete picture

Models + statistical tools applied to data **FILL IN THE GAPS**

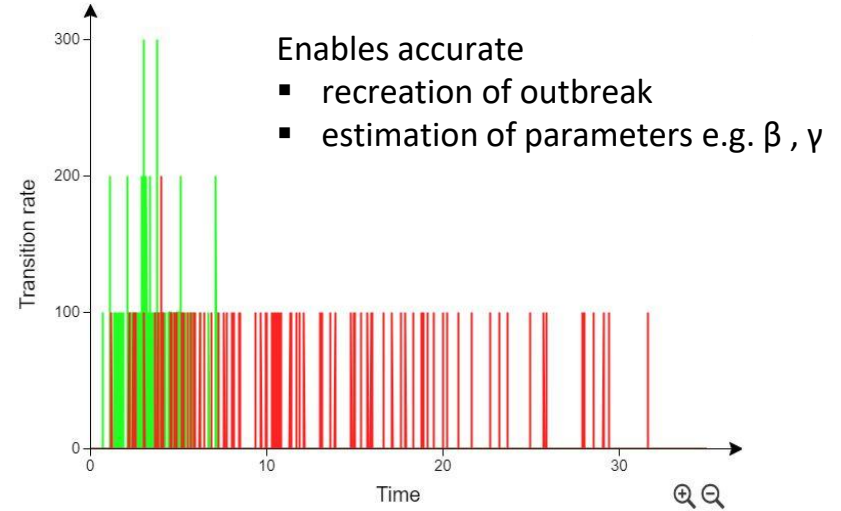
Uncertainty in our knowledge is better quantified but remains

Computational stats and epi-models

Intuition: frequent high quality observation

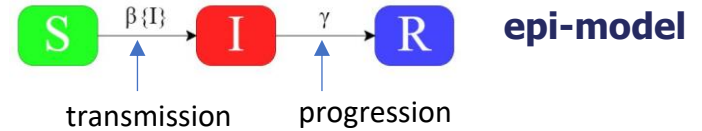
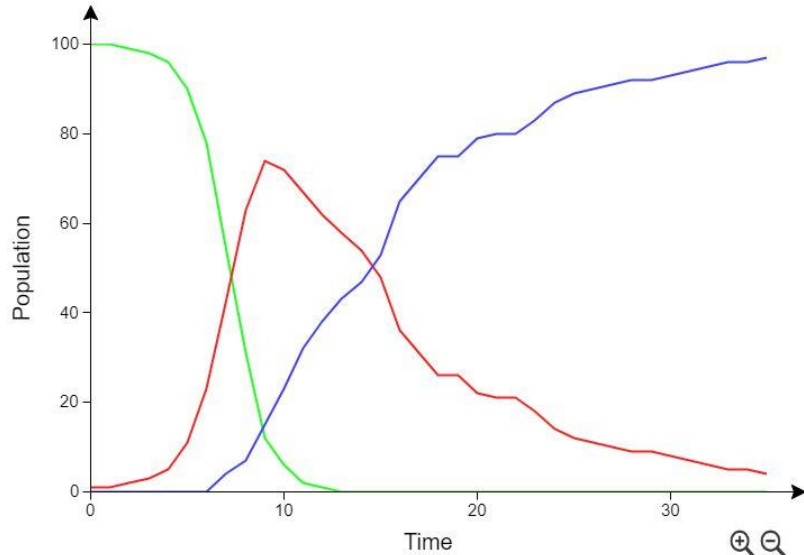


Translates into knowledge of (almost) all events

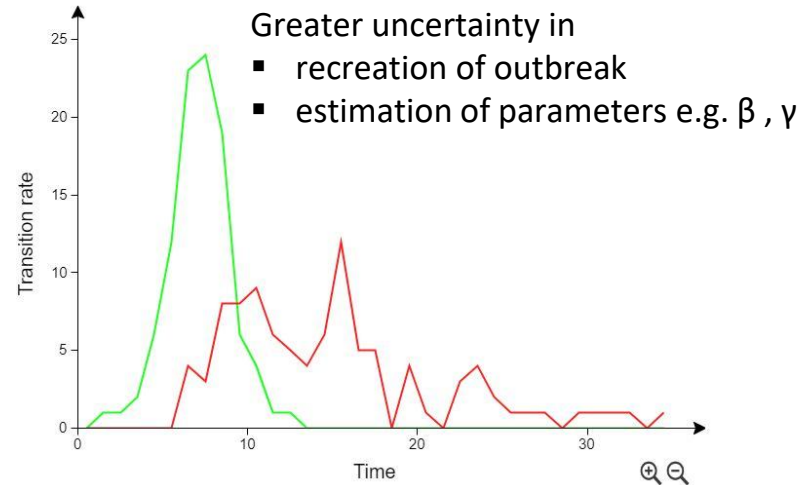


Computational stats and epi-models

Intuition: less frequent observation



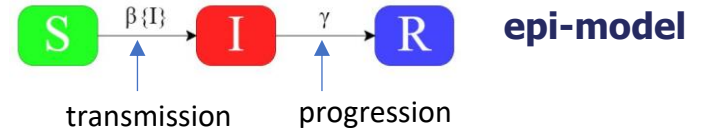
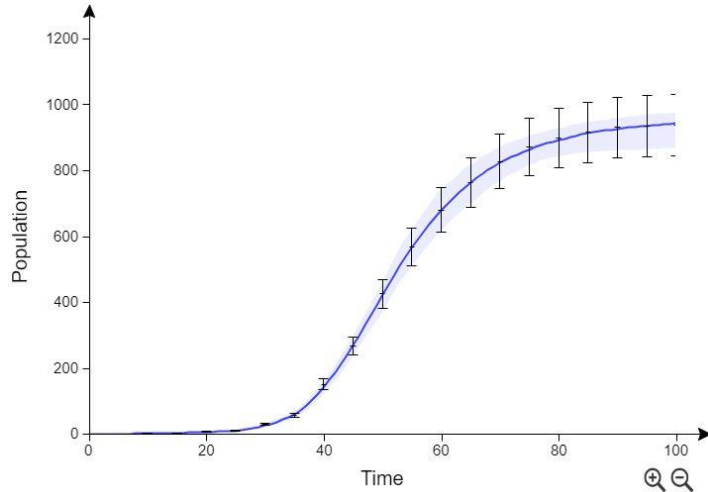
Translates into a (very) incomplete picture



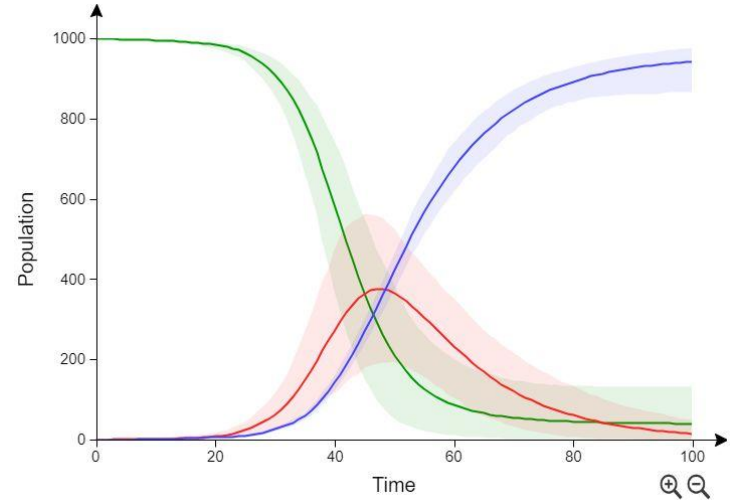
Computational stats and epi-models

In reality have **imperfect and partial** data

data: periodic observation of 'recovered' individuals



inference: estimated uncertainties



Developments and capabilities in inference for epidemic models

- Estimate hard to measure quantities
- Quantify disease risk from outbreak data to inform control
- Methods for faster computation: larger problems and integration of multiple data types
- Novel insights into disease dynamics – potential to inform control
- Prospects – current and future work

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Population modelling

Demographic stochasticity and realistic noise terms

Modelling heterogeneity

The need to represent heterogeneity

Spatial models

Spatial dynamics and spread

Individual and agent-based models

Individual behaviours shape system dynamics

Assessing model fit to data

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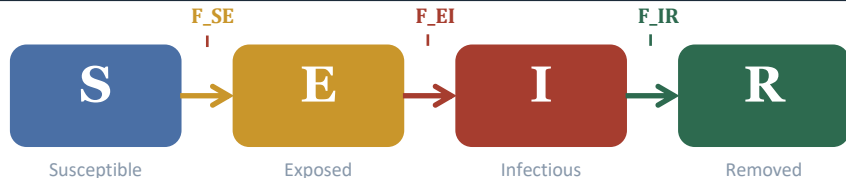
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The SDE-SEIR (non-spatial/population level) Model

Demographic stochasticity via Itô SDEs — three independent Wiener processes drive three reaction fluxes



Three reaction fluxes (Chemical Langevin Equation)

$$F_{SE} = \beta \cdot S \cdot I / N \cdot dt + \sqrt{(\beta \cdot S \cdot I / N)} \cdot dW_{SE}$$

$S \rightarrow E$: density-dependent infection; variance \propto flux magnitude

$$F_{EI} = \sigma \cdot E \cdot dt + \sqrt{(\sigma \cdot E)} \cdot dW_{EI}$$

$E \rightarrow I$: linear transition; noise collapses to zero when $E = 0$

$$F_{IR} = \gamma \cdot I \cdot dt + \sqrt{(\gamma \cdot I)} \cdot dW_{IR}$$

$I \rightarrow R$: recovery; mirrors $E \rightarrow I$ structure

Parameters $\theta = (\beta, \sigma, \gamma, N, \rho, \phi, S_0, E_0, I_0)$

β — transmission rate (day^{-1})

N — total (closed) population

σ — $E \rightarrow I$ transition rate (day^{-1})

ρ — reporting probability $\in (0,1)$

State equations (Itô form, closed population $N = S+E+I+R$)

$$dS = -F_{SE}$$

$$dE = +F_{SE} - F_{EI}$$

$$dI = +F_{EI} - F_{IR}$$

$$dR = +F_{IR}$$

Euler-Maruyama discretisation:

Brownian increments $dW \sim N(0, \sqrt{\Delta t})$ drawn independently. Positivity enforced by reflection (clamp to zero); Conservation $S+E+I+R = N$ maintained exactly by setting $R = N-S-E-I$.

Natural Pest Control

Context, Challenge & the
Need for Archetype Models

Alexandridis et al. (2022)
Ecological Applications

Why Natural Pest Control Matters

Arthropod pests cause major crop losses worldwide. Predators and parasitoids suppress pest populations naturally — a sustainable alternative to pesticides.

Landscape Context Drives Outcomes

Landscape composition (noncrop habitat) and configuration (field edge density) regulate how pests and natural enemies move and interact across agricultural systems.

The Modeling Challenge — Enter Archetypes

Pest responses to landscape change are highly variable across systems — existing models are either too system-specific or too generic to be actionable.

Archetypes group systems sharing key biological traits into mechanistic models of intermediate generality, bridging this gap.

Defining Archetypes

Resident Pest (A1) vs. Transient Pest (A2) — key traits driving different landscape responses

Archetype A1 — Resident Pest

Pest overwinters: **IN CROP**

Enemy diet: **SPECIALIST**

Enemy dispersal: **PASSIVE (WIND)**

System Behaviour:

More noncrop habitat favours generalists, which outcompete the specialist enemy. Net effect: resident pest abundance is unchanged by landscape complexity.

Archetype A2 — Transient Pest

Pest overwinters: **IN NONCROP HABITAT**

Enemy diet: **SPECIALIST (FLEXIBLE)**

Enemy dispersal: **PASSIVE (WIND)**

System Behaviour:

Pest migration diversifies the specialist's diet, decoupling it from pest density. Higher field edge density boosts generalists and suppresses the transient pest; noncrop habitat proportion alone has no net effect.

Stochastic Differential Equation Models

Full SDE for Archetype A1 — deterministic dynamics (black) plus stochastic noise terms (gold) | A2: set $\varepsilon_s = 0$

Archetype A1 — full stochastic differential equations (Alexandridis et al. 2022, Fig. 2c)

■ deterministic

■ stochastic noise

$$d\mathbf{P}(\mathbf{t}) = (a\mathbf{P} - \mu_p \mathbf{P} - f_s \mathbf{P}\mathbf{S}/(\mathbf{P}+\mathbf{K}_s) - f_g \mathbf{P}\mathbf{G}/(\mathbf{P}+\mathbf{K}_g) + v_p \mathbf{P}_0 - v_p \mathbf{P}) dt$$

$$+ \sqrt{a\mathbf{P}} dB_1(\mathbf{t}) - \sqrt{\mu_p \mathbf{P}} dB_2(\mathbf{t}) - \sqrt{f_s \mathbf{P}\mathbf{S}/(\mathbf{P}+\mathbf{K}_s)} dB_3(\mathbf{t}) - \sqrt{f_g \mathbf{P}\mathbf{G}/(\mathbf{P}+\mathbf{K}_g)} dB_4(\mathbf{t}) + \sqrt{v_p \mathbf{P}_0} dB_5(\mathbf{t}) - \sqrt{v_p \mathbf{P}} dB_6(\mathbf{t})$$

Pests

$$d\mathbf{S}(\mathbf{t}) = (-\mu_s \mathbf{S} + \varepsilon_s f_s \mathbf{P}\mathbf{S}/(\mathbf{P}+\mathbf{K}_s) + v_s \mathbf{S}_0 - v_s \mathbf{S}) dt$$

$$- \sqrt{\mu_s \mathbf{S}} dB_7(\mathbf{t}) + \sqrt{\varepsilon_s f_s \mathbf{P}\mathbf{S}/(\mathbf{P}+\mathbf{K}_s)} dB_8(\mathbf{t}) + \sqrt{v_s \mathbf{S}_0} dB_9(\mathbf{t}) - \sqrt{v_s \mathbf{S}} dB_{10}(\mathbf{t})$$

Specialist
predators

$$d\mathbf{G}(\mathbf{t}) = (-\mu_G \mathbf{G} + v_g \mathbf{G}_0 - v_g \mathbf{G}) dt$$

$$- \sqrt{\mu_G \mathbf{G}} dB_{10}(\mathbf{t}) + \sqrt{v_g \mathbf{G}_0} dB_{11}(\mathbf{t}) - \sqrt{v_g \mathbf{G}} dB_{12}(\mathbf{t})$$

Generalist
predators

Demographic Noise terms: $dB_i(\mathbf{t})$ — independent Gaussian white noise, drawn from $N(0, \sqrt{dt})$ for each \mathbf{t} and $i = 1\dots 12$

Parameter Glossary

$\mathbf{P}, \mathbf{S}, \mathbf{G}$	Pest, specialist & generalist enemy density in crop
\mathbf{a}	Pest intrinsic growth rate
μ_p, μ_s, μ_G	Natural mortality rates

f_s, f_g	Functional response attack rates (type II)
K_s, K_g	Half-saturation constants ($\frac{1}{2}$ max attack rate)
ε_s	Specialist conversion efficiency (0 in A2)

u_p, u_s, u_g	Crop–noncrop connectivity rates
P_0, S_0, G_0	Noncrop habitat carrying capacities
$dB_i(\mathbf{t})$	Independent Gaussian white noise increments

Estimating dynamics of AMR horizontal gene transfer & demography

**Understanding population-level
persistence of anti-microbial resistance:
the need to quantify the dynamics of
mobile genetic elements**

Sonia Mitchell, Glenn Marion, Lucio Marcello (BioSS)

Lesley Smith, Mike Hutchings (SRUC)

Alex Corbishley (University of Edinburgh)

Estimating dynamics of AMR

- Modelling population dynamics and horizontal transfer of AMR genes
- Estimation of key characteristics from timeseries data
- Application to experimental data

AMR gene demography and HGT

A simple model – demography and horizontal gene transfer

Resistant
bacteria

$$\frac{dR}{dt} = \alpha e^{-\phi} R \left(1 - \frac{R+S}{K} \right) + \frac{\beta_H}{K} SR - \gamma R - \mu(1+\epsilon)R$$

Births

HGT

R-gene
loss

Deaths

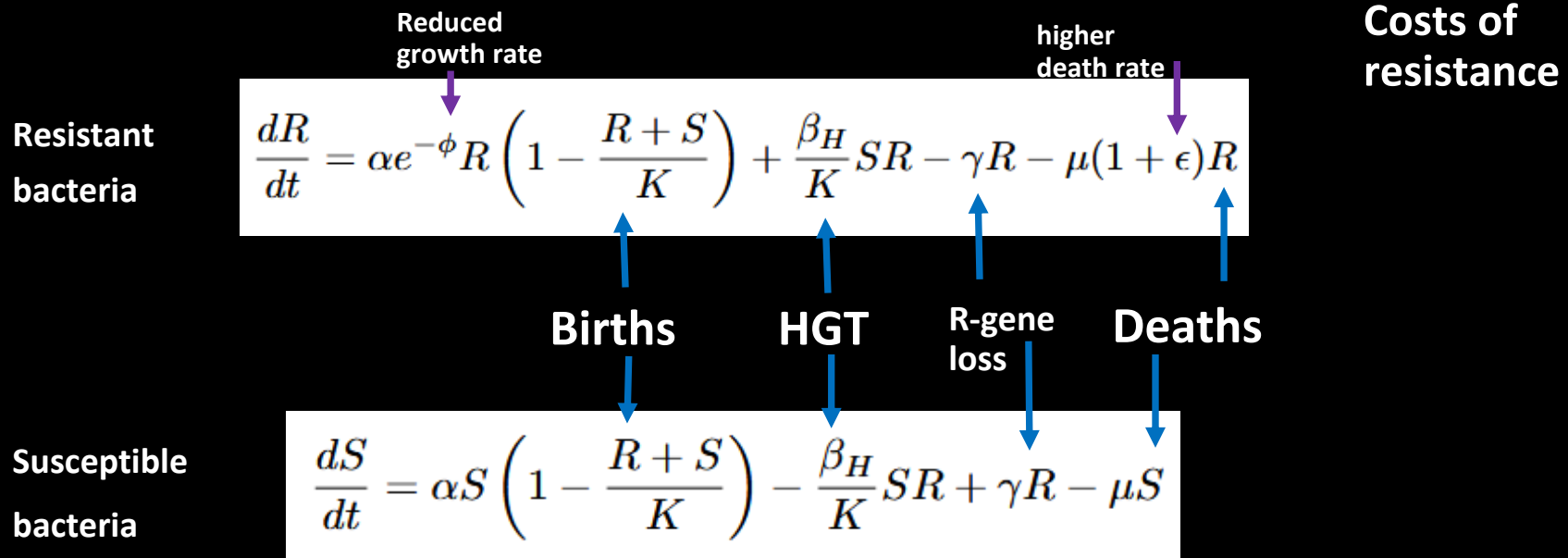
Susceptible
bacteria

$$\frac{dS}{dt} = \alpha S \left(1 - \frac{R+S}{K} \right) - \frac{\beta_H}{K} SR + \gamma R - \mu S$$

Estimating dynamics of AMR horizontal gene transfer & demography

AMR gene demography and HGT

A simple model – demography and horizontal gene transfer



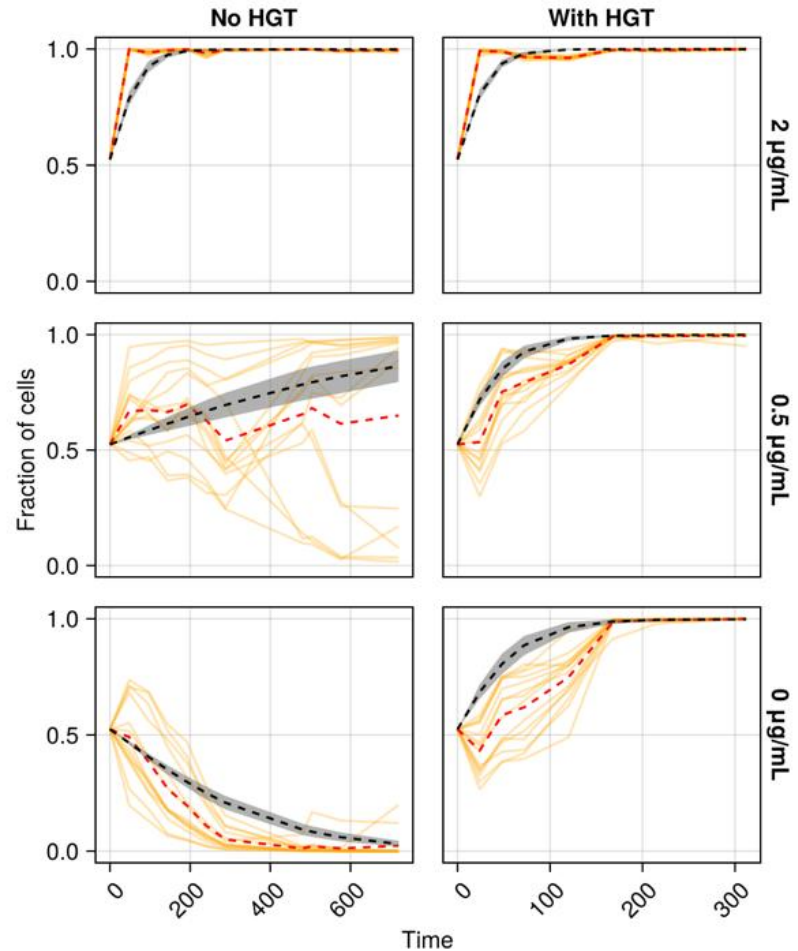
Estimating dynamics of AMR horizontal gene transfer & demography

Can estimate parameters from experimental data

But estimates do not account for variation in experimental outcomes

Demographic stochasticity very small

Need to explore environmental noise on different aspects of the model



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Age-Stratified COVID-19 Model

9 Compartments
Across 18 Age Groups

S → E
Force of infection $\lambda_{a,t}$ drives exposure

E branches
Asymptomatic (A) or Infectious (I) — age-dependent

I → C → H → D
Clinical pathway to hospitalisation & death

Surveys
PCR & seroprevalence link model states to data
Pooley, Doeschl-Wilson & Marion
Phil. Trans. R. Soc. A (2022)

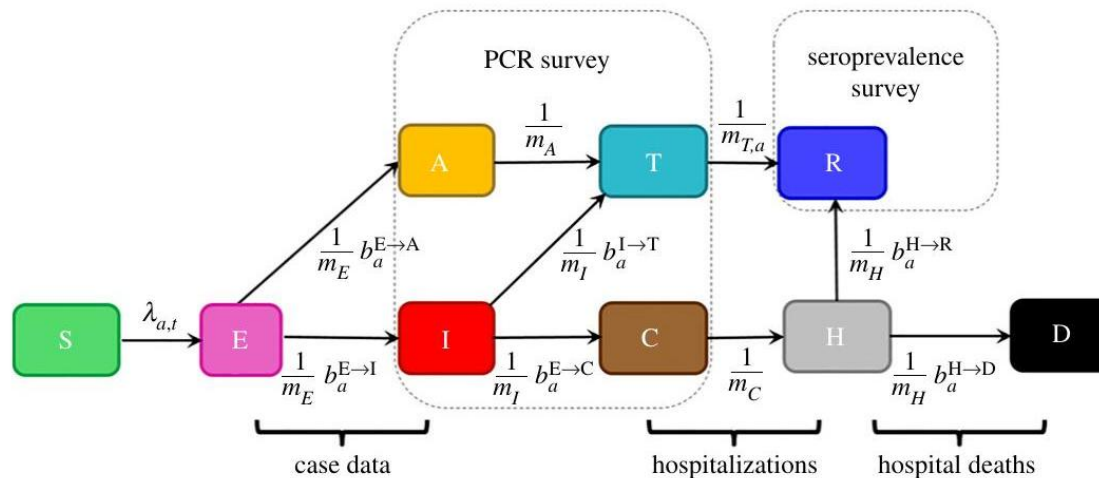


Figure 1. The compartmental model. The compartments are defined as follows: S: susceptible, E: exposed, A: asymptomatic, I: infectious, T: PCR+, not infectious, C: isolated (non-hosp.), H: hospitalised, R: recovered, D: dead

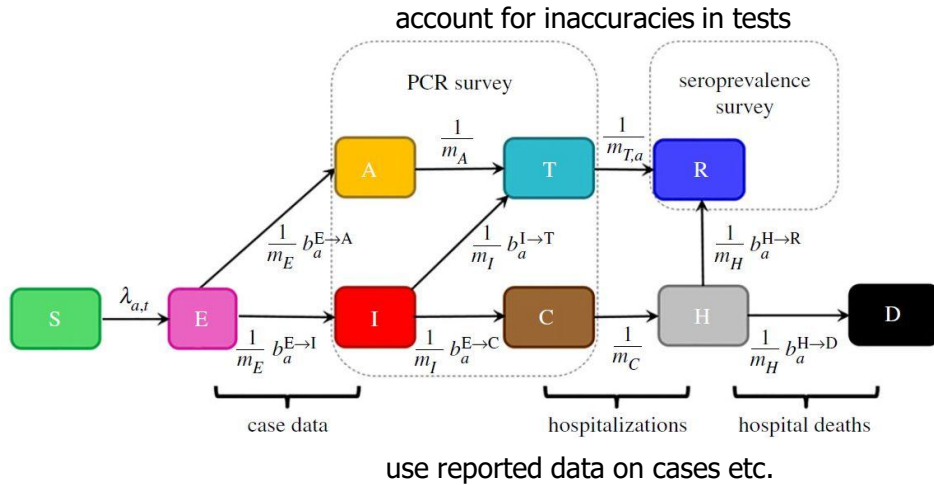


Key insight: All branching probabilities and transition rates are **age-stratified (subscript a)** — 18 age bands from 0–4 to 80+ plus care home residents.

Data linkage: PCR surveys → A, I, T, C states | Seroprevalence → R state | Case / hospital / death records → E→I, C→H, H→D transitions.

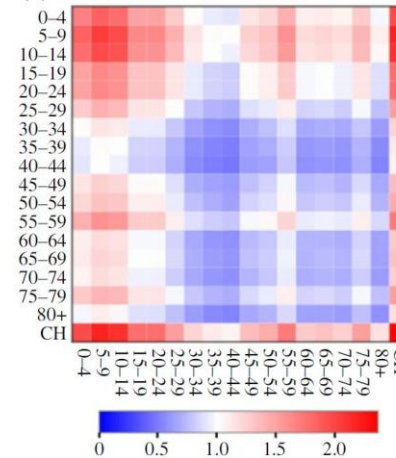
Methods for faster computation: larger problems and integration of multiple data types

- National-scale COVID models combining multiple data



- Estimation of parameters: age-related contacts

Pre-pandemic based on the BBC Pandemic study



Changes relative to pre-pandemic contact patterns

Contact patterns critical to effective modelling

Many other cases where need to represent heterogeneity

Natural Pest control

- many different species and/or
- variation across and between landscapes

Antimicrobial Resistance (AMR)

- hundreds of species of bacteria and strains
- many resistance genes
- multiple antimicrobial agents

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Spatial Risk from Small Outbreaks

*Classical Swine Fever
East Anglia, UK (2000)*

Only 16 farms infected

1,703 farms at risk in region

Detection times only (no infection times)

Goal: spatial risk maps for control

Gamado, Marion & Porphyre
Front. Vet. Sci. (2017)

The Challenge — Reliable Inference from Limited Data SIR model

Why small outbreaks matter

Large outbreaks (FMD 2001: £8bn; CSF Netherlands 1997: £1.1bn) are rare. Emerging pathogens typically cause small, repeated, localised incursions — but these are what we observe first.

The inference problem

Infection times are unobserved. Only farm detection times and locations are available. Data-augmentation MCMC treats missing infection times as latent variables and samples them jointly with model parameters θ .

Why kernel choice matters

The spatial transmission kernel $h(d)$ determines how infection risk decays with distance. Four candidates (K_1 – K_4) are fitted — and predicted risk maps differ dramatically between them.

Four Spatial Transmission Kernels $h(d)$ — where d = Euclidean distance between farms

$$K_1 \text{ — } \exp\{-\tau d\}$$

Exponential — fastest decay

$$K_2 \text{ — } 1 / (1 + (d/\delta))^\tau$$

Power-law (Cauchy-type) — moderate tail

$$K_3 \text{ — } 1 / (1 + d/\delta)$$

Cauchy — heaviest tail (K_2 with $\tau=1$)

$$K_4 \text{ — } 1 - \exp(-(d/\delta)^\tau)$$

Bounded — emphasises short-range

Inference pipeline

Farm locations
+ detection times R

Data-augmented
MCMC samples θ, I

Posterior predictive
simulations
(Gillespie)

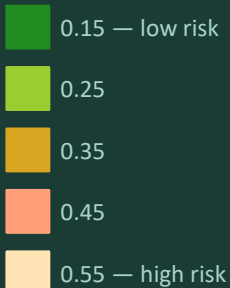
Farm-level
risk maps

Key finding: Latent residuals (Infectious Link Residuals, ILRs) outperform DIC for kernel selection, especially for small outbreaks. For ≥ 20 cases, ILRs select the correct kernel $\geq 90\%$ of the time. Risk maps are highly sensitive to which kernel is chosen — making reliable model selection critical for disease control decisions.

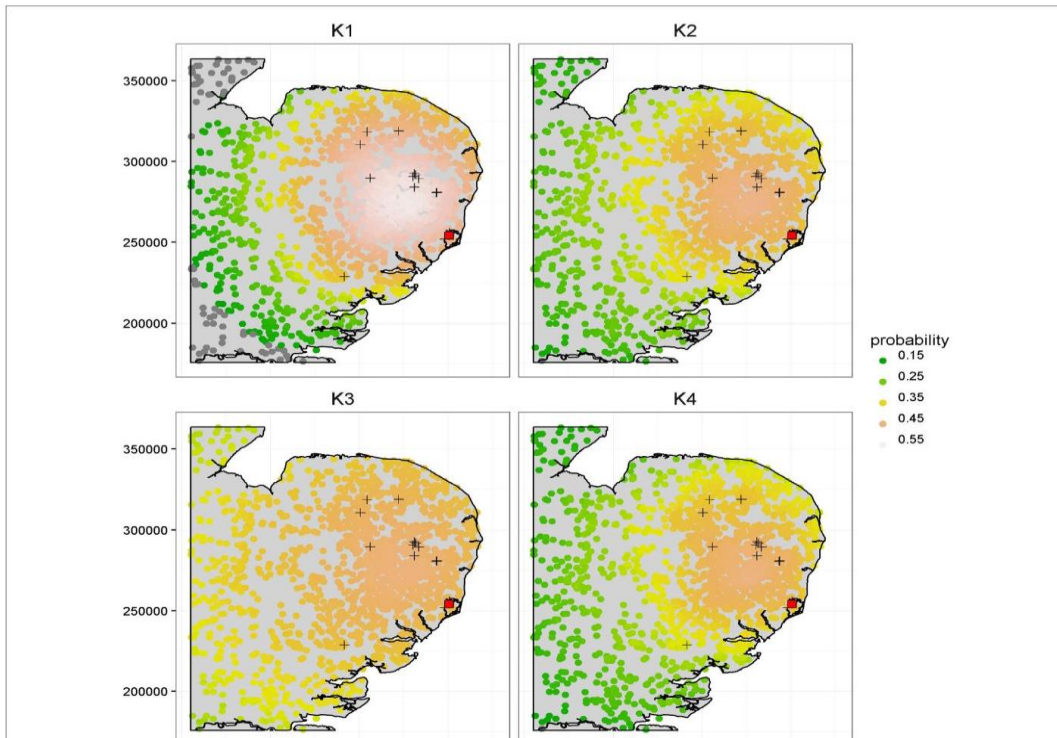
Predicted Infection Risk Maps

Figure 4 — CSF East Anglia at $t = 90$ days

Dot colour = probability of infection



+ = detected case
 ■ = index case (red)



K₁
 Fastest decay — high risk tightly localised around index

K₂
 Moderate tail — ILRs prefer this; similar to K₄

K₃
 Heaviest tail — predicts highest risk at all distances

K₄
 Short-range emphasis — similar risk profile to K₂

Inferring Disease Spread with Unknown Populations at Risk

iPAR framework — Catterall, Porphyre & Marion (2025) PLoS Comput. Biol.

The Problem

Spatial epidemic models require knowledge of where the host population lives — but this is often unavailable.

Wildlife populations (e.g. wild boar) are poorly mapped. Livestock records may be incomplete or private.

Case-only data: disease reports exist, but the distribution of susceptible individuals does not.

Without population data, existing transmission models cannot be reliably applied.

The iPAR Solution

Landscape covariates

Land use and other spatial data proxy the unknown host distribution.

Patch-based SI model

Estonia divided into 575 patches (10 km²). Each patch is susceptible or infected.

Inferred surfaces

Susceptibility and infectivity surfaces estimated from case data, not assumed.

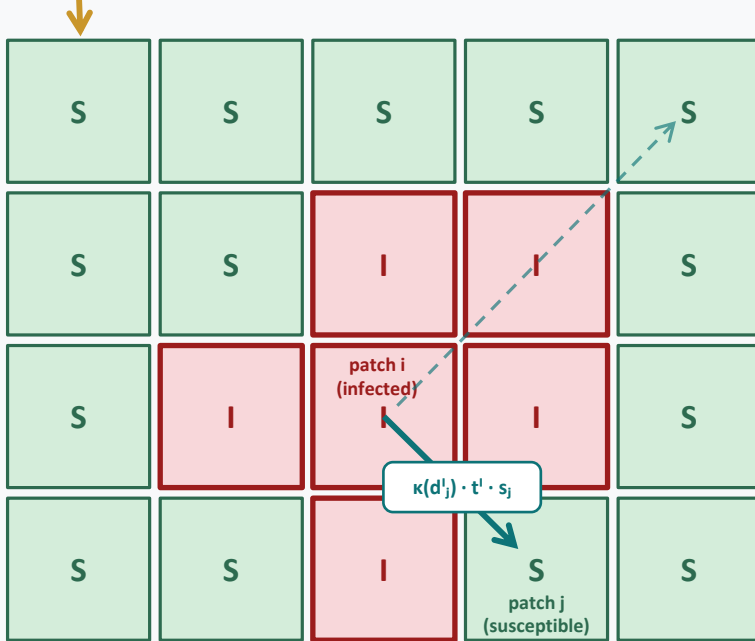
Bayesian MCMC

Data-augmentation MCMC fits the model to spatio-temporal case reports.

Spatial Model Structure: Patches, Transmission & Covariate Surfaces

Force of infection · Susceptibility · Infectivity — Catterall et al. (2025)

ϵ — external infection rate applied to every susceptible patch



Secondary (kernel)



Strong at short range



weaker at longer ranges



Susceptible (S)



Infected (I)

① Force of Infection on susceptible patch i

$$f_i = \epsilon s_i + \rho \sum_j s_i \cdot t_j \cdot \kappa(d_{ij})$$

ϵ — background infection rate

ρ — secondary transmission rate

$\kappa(d_{ij})$ — decays with distance d_{ij}^1

② Patch Susceptibility s^i — weighted by land-use composition

$$s_i = \sum_l h_{il} \sigma_l \quad \text{where } \sum_l \sigma_l = 1 \quad (\text{for identifiability})$$

σ_1

Urban

σ_2

Agri

σ_3

Broadleaf

σ_4

Conifer

Semi-nat
 σ_5

σ_6

Wetland

③ Patch Infectivity t^i — same covariate structure as susceptibility

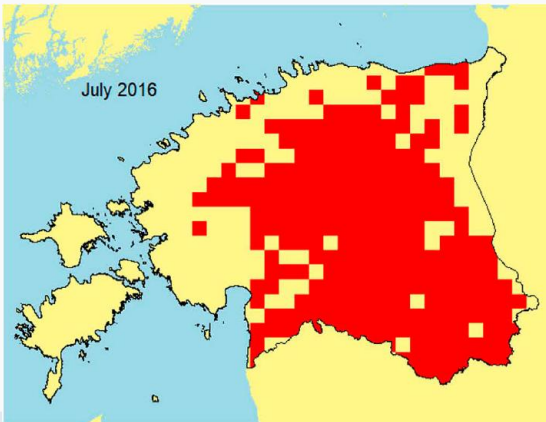
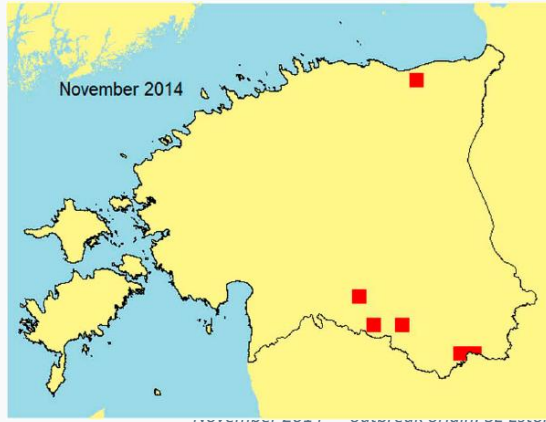
$$t_i = \sum_l h_{il} \gamma_l \quad \text{where } \sum_l \gamma_l = 1 \quad (\text{for identifiability})$$

h_{il} — proportion of patch i with land use l

γ_l — infectivity weight of land use l (estimated from outbreak data)

Case Study: African Swine Fever in Estonian Wild Boar (2014–2019)

Spatial spread of ASF — Fig. 6, Catterall et al. (2025)



Outbreak Context

Disease: African Swine Fever (ASF) — near 100% fatal in wild boar; no vaccine available.

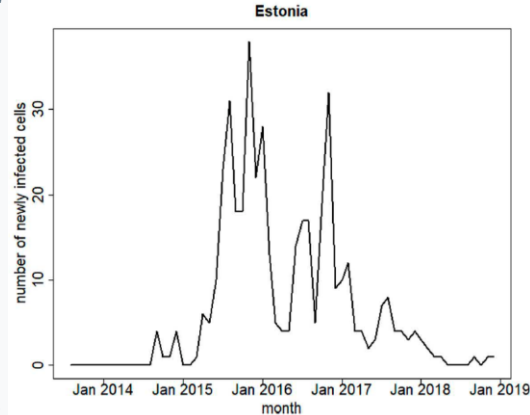
Entry: First case detected in SE Estonia (Nov 2014), introduced from Russia via Latvia.

Scale: 2,045 wild boar cases reported 2014–2019 across 575 × 10 km patches covering Estonia.

Control: Intensive hunting campaigns reduced wild boar density; decline apparent in later outbreak data.

Data: Monthly case reports with locations.

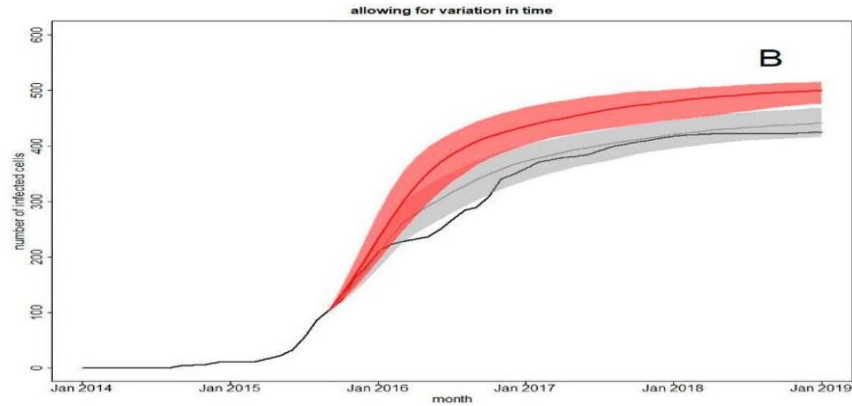
Outbreak Incidence Curve (Fig. 6, bottom right panel)



Monthly case reports 2014–2019; y-axis: new cases per month; sharp decline after 2017 reflects control

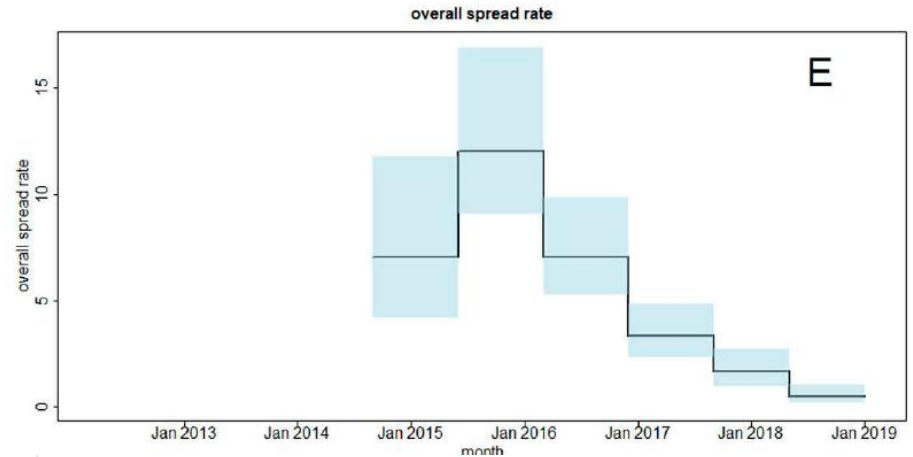
Results: Model Predictions

Model predictions – non-spatial



Model fit: Heterogeneous iPAR model (fitted to early data up to Sep 2015) projects cumulative patch incidence with 95% credible intervals. The varying-in-time model fitted to the full data captures the post-2017 decline in spread rate — evidence of successful population control.

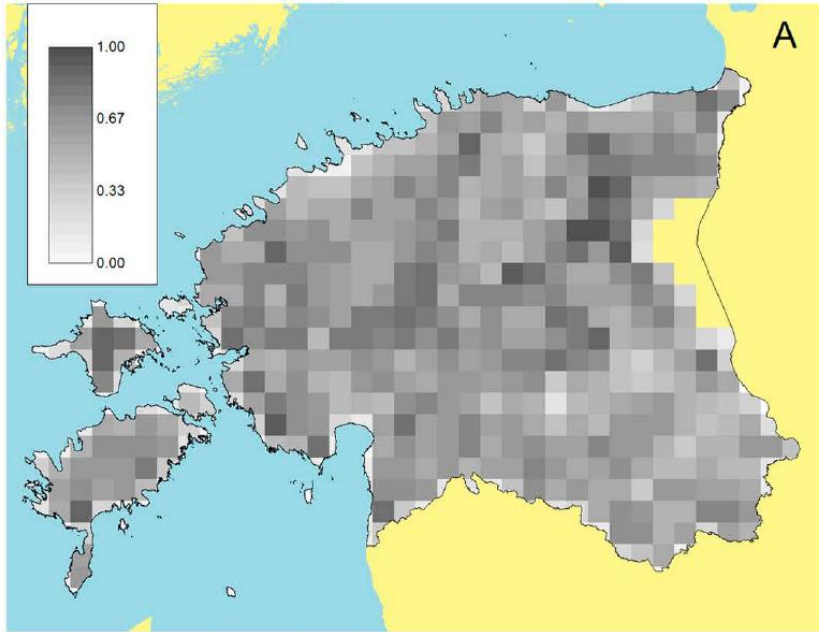
Varying-in-time model fitted to full Estonian ASF outbreak – accounts for hunting campaign



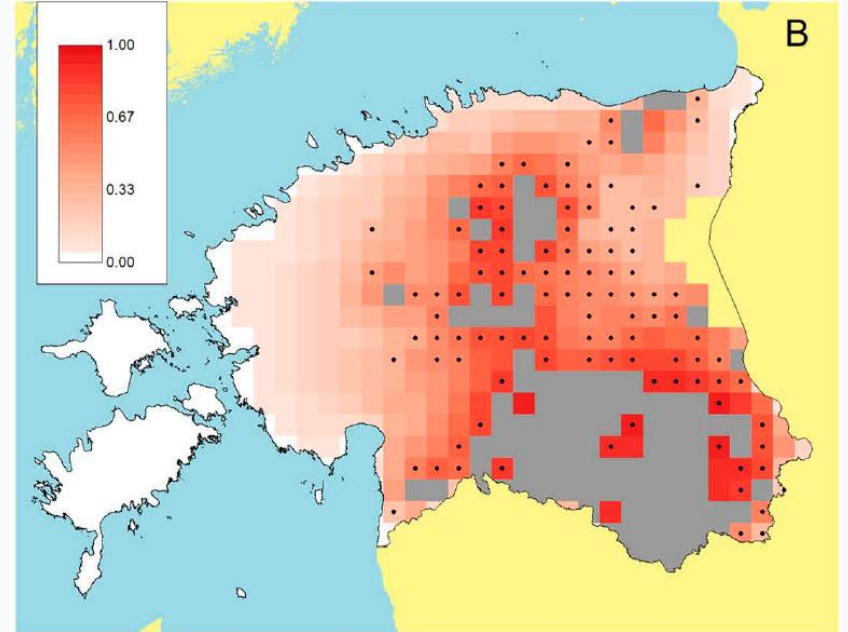
Spread rate: $\beta(t)$ declines markedly from 2017 onwards — coinciding with intensified hunting campaigns. This provides statistical evidence that population reduction through culling reduced disease transmission rates.

Results: Model Predictions & Susceptibility Map

Estimated susceptibility map and model output

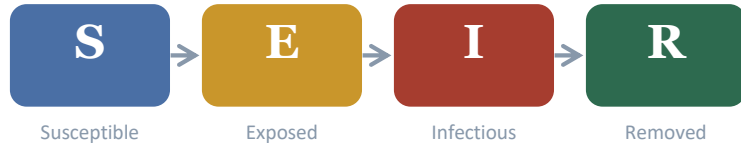


Estimated susceptibility surface across Estonia; higher values = greater risk of infection incursion.



Predicted probability of spread (red) & observed spread (dots) from known infections (grey)

The Spatial SEIR Transmission Model (semi-Markov)



Probability of exposure during $[t, t+dt)$:

$$p(j, t) = \{ \alpha + \beta \sum_{i \in I(t)} K(d_{ij}, \kappa) \} dt$$

α primary rate · β contact rate · $K(d_{ij}, \kappa)$ spatial kernel

Three competing spatial kernels $K(d, \kappa)$:

A — Exponential

$$K(d, \kappa_1) = \exp(-\kappa_1 d)$$

Locally bounded; probability of long-range transmission decays rapidly.

B — Cauchy-type

$$K(d, \kappa_2) = 1 / (1 + d/\kappa_2)$$

Heavy tail; long-range transmission remains substantial. Rejected for hogweed (§4).

C — Power-law

$$K(d, \kappa_3) = d^{-\kappa_3}$$

Scale-free; intermediate tail behaviour. Comparable fit to A for hogweed.

Latent Period (time in class E)

$$x \sim \text{Gamma}(\mu, \sigma^2) \quad f_E(x; \mu, \sigma^2) = x^{\mu/\sigma^2 - 1} e^{-x\mu/\sigma^2} / [(\sigma^2/\mu)^{\mu/\sigma^2} \Gamma(\mu^2/\sigma^2)]$$

μ = mean · σ^2 = variance · parameterised for interpretability

Infectious Period (time in class I)

$$x \sim \text{Weibull}(\gamma, \eta) \quad f_I(x; \gamma, \eta) = (\eta/\gamma) \cdot (x/\gamma)^{\eta-1} \cdot e^{-(x/\gamma)^\eta}$$

γ = shape · η = scale · fitted in all model variants

Case Study: Giant Hogweed SI Model with Site Suitability

$$p(j, t) = c_j \{ \alpha + \beta \sum K(d_{ij}, \kappa) \} dt$$

$c_j \in [0,1]$ — habitat suitability score (temperature, altitude, other covariates; Catterall et al. 2012). E and I merged into one class (no recovery R). Six model variants: 3 kernels × ±suitability.

Inference: Data augmentation MCMC samples from the joint posterior $p(\theta, Z | y)$, where Z is the complete (partially unobserved) epidemic trajectory and y the interval-censored observations. Sojourn times are interval-censored; infection times are latent variables sampled alongside model parameters.

Opportunities and barriers in application of stochastic differential equations to agriculture and ecology

glenn.marion@bioss.ac.uk

Population modelling

Demographic stochasticity and realistic noise terms

Modelling heterogeneity

The need to represent heterogeneity

Spatial models

Spatial dynamics and spread

Individual and agent-based models

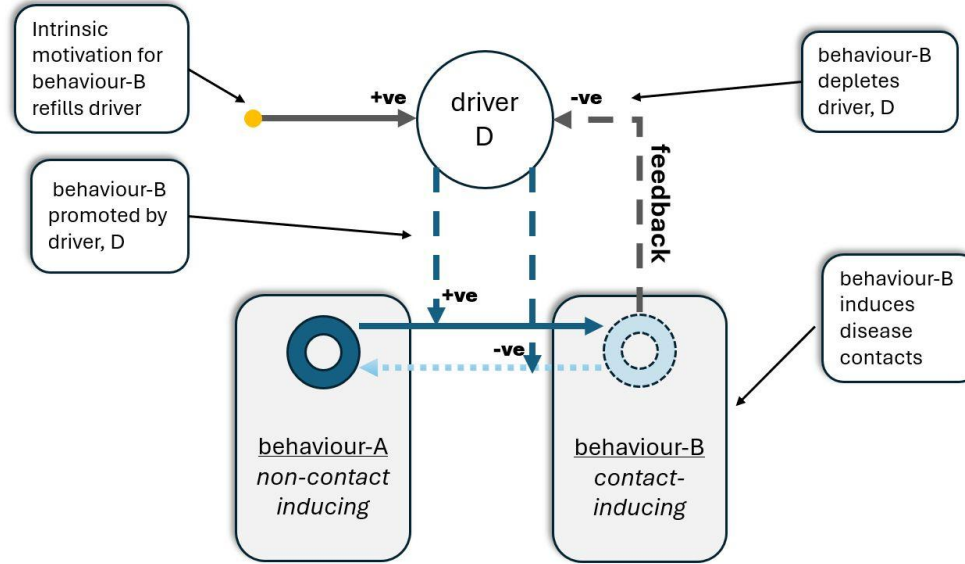
Individual behaviours shape system dynamics

Assessing model fit to data

Challenges for modelling fitting
Inference for spatial models
Assessing model fit

Individual behavioural drivers for disease contact processes

- Disease controls typically aim to reduce contact/contact behaviours
- **But** these behaviours done for a reason
- **So** expect pushback and compensatory behaviours in response
- Agent-based modelling of systems allows for exploration of these dynamics and the potential of different control measures
- Ideas have been applied to livestock disease spread via cattle trading
 - Showed impact of changing trading behaviour
 - Strong benefit of sharing information on disease risk and how this changes trading behaviours



individual behavioural states, transitions and driver dynamic

individuals exhibiting
behaviour-A
non-contact inducing

**behavioural
transitions governed
by driver model**

individuals exhibiting
behaviour-B
contact inducing

#individuals
susceptibles S_A, S_B
infectious I_A, I_B

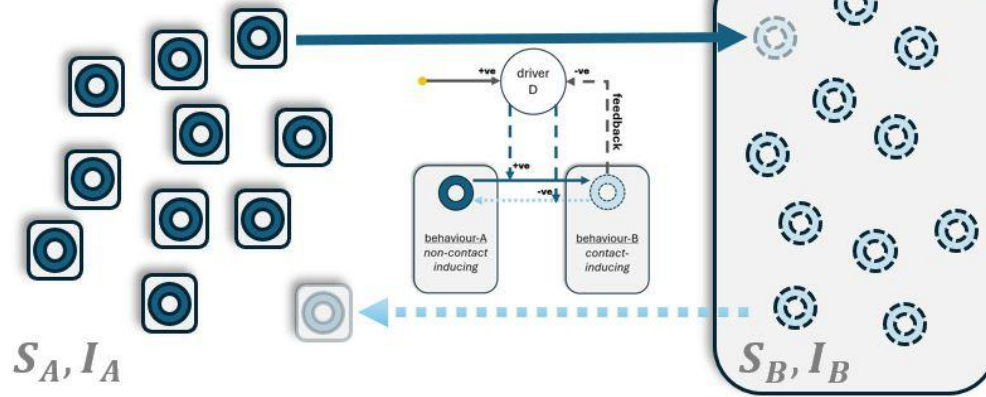
S_A, I_A

S_B, I_B

SIR disease
dynamics

progression γI_A

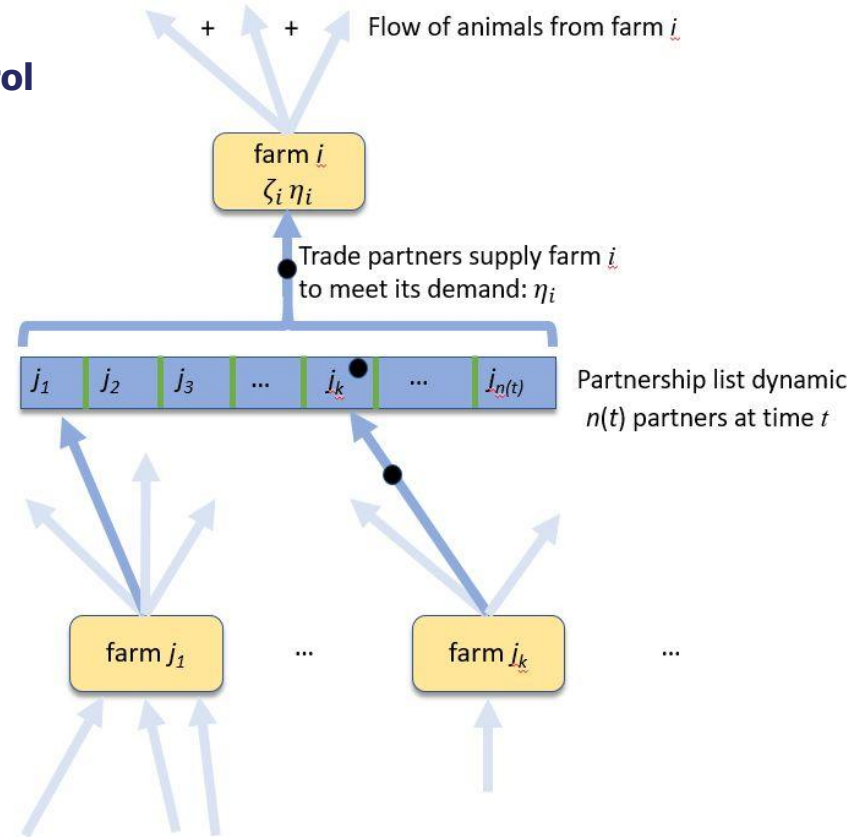
transmission $\beta S_B I_B$
progression γI_B



Initial attempt at systems approach to disease control

Generative model of cattle trade between farms

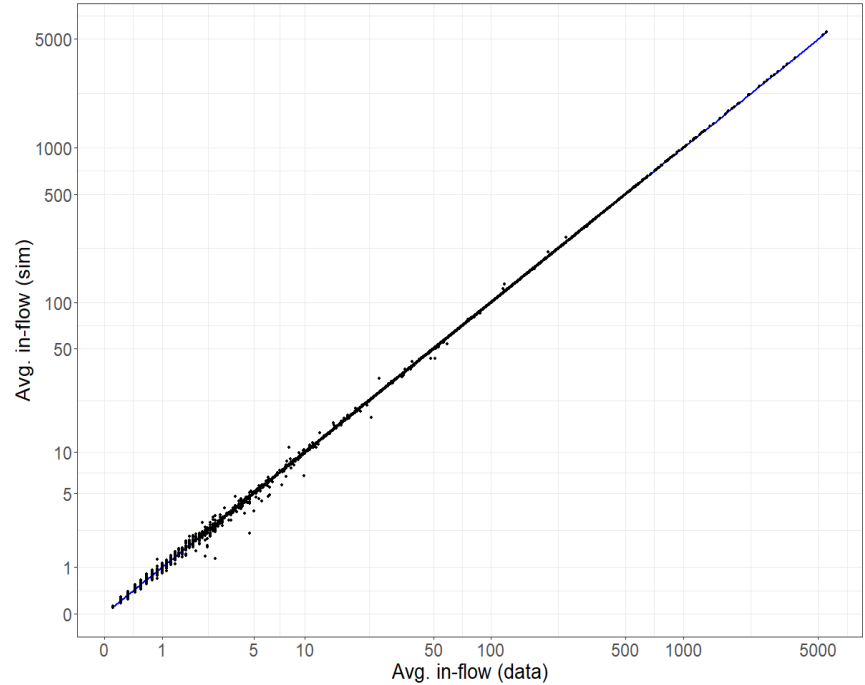
- given farm generates supply and/or demand
- those with demand satisfy this by trade with farms with available supply
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- get power-law like distributions – a few large players with many smaller



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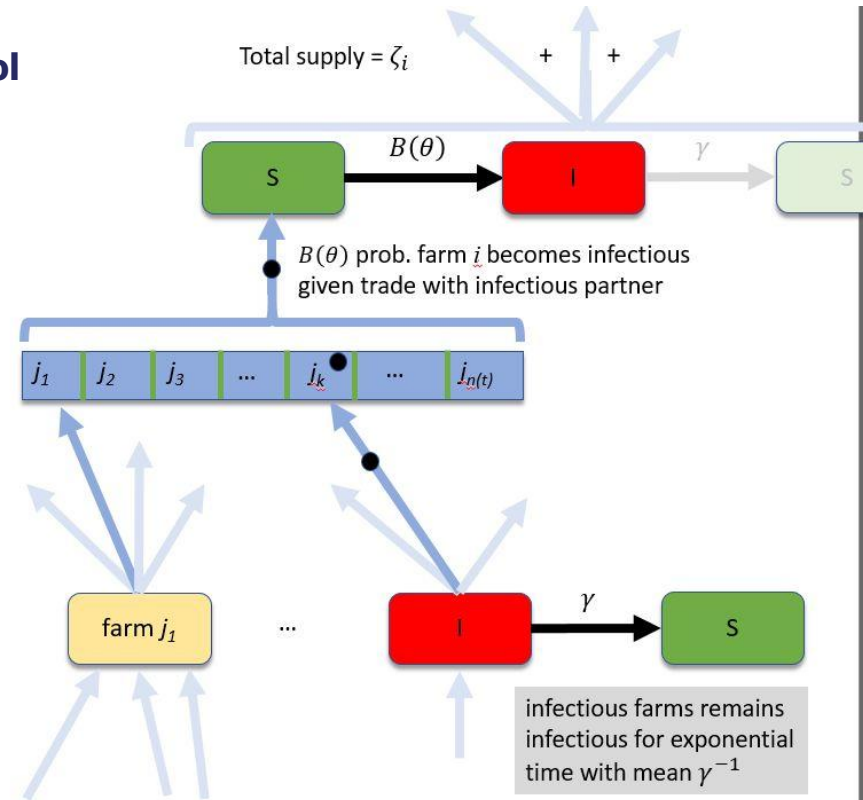
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- those with demand satisfy this by trade with farms with available supply
- rates determined from CTS data – currently for Scotland – *digital twin*
- get power-law like distributions – a few large players with many smaller
- **approach captures key features**



Initial attempt at systems approach to disease control

Now just add disease dynamics!

- SIS dynamic – recovery rate γ
- Trade with infected farms can lead to transmission – dependent on batch size B
- Possible controls
 - Biosecurity – increase recovery rate
 - Test (and cull) on movement
 - Change trading behaviour
 - Combinations on the above



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Latent Residuals for Fitted Model Diagnostics

*The core idea: embed classical
residuals within Bayesian inference*

The Assessment Gap

Bayes factors are sensitive to priors and computationally prohibitive. The DIC is not uniquely defined for partially observed processes. Posterior predictive checks can be insensitive to model choice — even when kernels are very different (§4.2).

The Functional Model (Cox & Snell 1968)

$$\mathbf{Z} = \mathbf{h}_{\theta}(\tilde{\mathbf{r}}) \quad \text{where } \tilde{\mathbf{r}} \sim U(0,1)$$

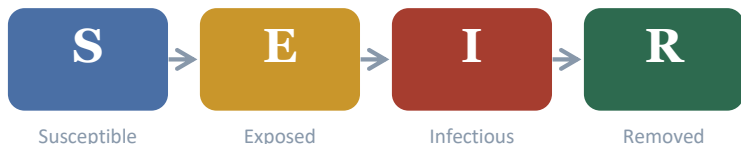
\mathbf{Z} — complete epidemic data θ — model parameters

Any stochastic model realisation can be written as a deterministic function of uniform random variables. The residuals $\tilde{\mathbf{r}}$ have known sampling properties — which can be tested.

Link to Sellke Thresholds

Sellke (1983) showed that each exposure event can be triggered by a threshold drawn from $U(0,1)$ applied to the integrated infectious challenge $A(t)$. This is precisely the ETR construction used here (eq. 2.5). The earlier use of Sellke thresholds as Bayesian residuals (Gibson et al. 2006) required imputation even for uninfected individuals — a problem for small epidemics. The present construction avoids this: residuals are imputed only at each infection event.

The Spatial SEIR Transmission Model



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Inference: Data augmentation MCMC samples from the joint posterior $p(\theta, Z | y)$, where Z is the complete (partially unobserved) epidemic trajectory and y the interval-censored observations. Sojourn times are interval-censored; infection times are latent variables sampled alongside model parameters.

Three Latent Residual Types — Construction & Diagnostic Power

 \tilde{r}_1

Exposure Time
Residuals (ETR)

Construction:

For the k th exposure, r_{1k} is set against the integrated infectious challenge $A(t)$:

$$1 - e^{-A(t)} > r_{1k} \rightarrow \text{exposure at } t_k$$

Targets:

Overall timing of exposures

Diagnostic intuition:

If the force of infection is correctly specified, intervals between exposures integrate to $\text{Exp}(1)$ — the threshold r_{1k} captures this. Based directly on Sellke (1983).

 \tilde{r}_2

Infection-Link
Residuals (ILR)

Construction:

Links are ranked by kernel weight $p(ij) \propto K(d_{ij})$. The rank of the observed link among all $S \times I$ links gives r_{2k} :

$$r_{2k} \sim U(\sum p(\alpha), \sum p(\alpha) + p(s'))$$

Targets:

The spatial kernel $K(d_{ij}, \kappa)$

Diagnostic intuition:

Ordering links by kernel weight means a too-rapidly-decaying kernel concentrates residuals at extremes; a too-slowly-decaying kernel shows a scarcity at extremes — opposite, diagnosable patterns (Fig. 2).

★ Key diagnostic for spatial kernel choice

 \tilde{r}_3

Latent Time
Residuals (LTR)

Construction:

For exposed individual k , r_{3k} is set against the accumulated pressure of becoming infectious $Q(t)$:

$$1 - e^{-Q(t)} > r_{3k} \rightarrow \text{infectious at } t'_k$$

Targets:

Latent period distribution $f(\cdot)$

Diagnostic intuition:

If the latent-period distribution is mis-specified, the LTRs depart from $U(0,1)$. Correctly specified, they are exactly uniform — a cleanly targeted diagnostic.

The General Principle: Every Stochastic Realisation Built from r.v. with known distribution(s)

Any stochastic model realisation $\mathbf{Z} = \mathbf{h}_\theta(\tilde{\mathbf{r}})$ where $\tilde{\mathbf{r}} \sim \mathbf{U}(0,1)$ but other options may be preferred

Under the correct model, the imputed residuals $\tilde{\mathbf{r}}$ are exactly uniform.
Mis-specification \rightarrow systematic departure from $\mathbf{U}(0,1)$ \rightarrow detectable by classical tests.

① Any Stochastic Process or Model

- Epidemic model (SEIR, SI, SIR)
- Ecological invasion model
- Animal movement model
- Plant dispersal / colonisation
- Any Markov / point process
- Branching processes, renewal models

Discrete or continuous states and or time

② Design Targeted Residuals $\tilde{\mathbf{r}}$

- Partition $\tilde{\mathbf{r}}$ so each component corresponds to one model aspect
- Exposure times \rightarrow ETR (Sellke)
- Spatial links \rightarrow ILR (kernel)
- Sojourn times \rightarrow LTR (periods)
- Suitability / covariates $\rightarrow \tilde{r}_d, \dots$
- Any unknown latent process

*Design drives sensitivity:
partition matches structure.*

③ Test Against $\mathbf{U}(0,1)$ Classically

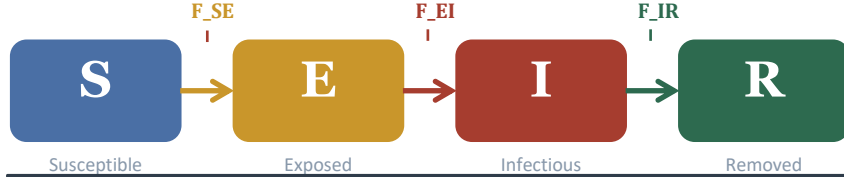
- Impute $\tilde{\mathbf{r}}$ from MCMC posterior
- Apply Anderson–Darling test
- Get posterior distribution of p-values
- $p(\mathbf{P}(\tilde{\mathbf{r}}) < 0.05 \mid \mathbf{y}) \rightarrow$ evidence measure
- Histogram shape reveals mis-spec type
- Extreme concentration or scarcity

*Addendum to existing MCMC —
no new algorithm needed.*

Key insight: the principle is universal. Any stochastic model realisation is built on a set of underlying uniform random numbers $\tilde{\mathbf{r}}$. Under the correct model these are exactly $\mathbf{U}(0,1)$.
Mis-specification is visible as a systematic, interpretable departure from uniformity.

The SDE-SEIR (non-spatial/population level) Model

Demographic stochasticity via Itô SDEs — three independent Wiener processes drive three reaction fluxes



Three reaction fluxes (Chemical Langevin Equation)

$$F_{SE} = \beta \cdot S \cdot I / N \cdot dt + \sqrt{(\beta \cdot S \cdot I / N)} \cdot dW_{SE}$$

$S \rightarrow E$: density-dependent infection; variance \propto flux magnitude

$$F_{EI} = \sigma \cdot E \cdot dt + \sqrt{(\sigma \cdot E)} \cdot dW_{EI}$$

$E \rightarrow I$: linear transition; noise collapses to zero when $E = 0$

$$F_{IR} = \gamma \cdot I \cdot dt + \sqrt{(\gamma \cdot I)} \cdot dW_{IR}$$

$I \rightarrow R$: recovery; mirrors $E \rightarrow I$ structure

Parameters $\theta = (\beta, \sigma, \gamma, N, \rho, \phi, S_0, E_0, I_0)$

β — transmission rate (day^{-1})

N — total (closed) population

σ — $E \rightarrow I$ transition rate (day^{-1})

ρ — reporting probability $\in (0,1)$

State equations (Itô form, closed population $N = S+E+I+R$)

$$dS = -F_{SE}$$

$$dE = +F_{SE} - F_{EI}$$

$$dI = +F_{EI} - F_{IR}$$

$$dR = +F_{IR}$$

Euler-Maruyama discretisation:

Brownian increments $dW \sim N(0, \sqrt{\Delta t})$ drawn independently. Positivity enforced by reflection (clamp to zero); Conservation $S+E+I+R = N$ maintained exactly by setting $R = N-S-E-I$.

Data and model fitting – fitted model matches data generation

Synthetic SDE trajectories → reported cases via Negative-Binomial

Data generation & observation model

① Observed only Recovered cases periodically

The CLE adds Wiener-process fluctuations to each reaction flux — demographic stochasticity. Even with identical parameters, every simulated epidemic trajectory is different. Variance \propto propensity (square-root diffusion).

② Observation noise

Only a fraction ρ of true recoveries ΔR are reported, and reporting itself is overdispersed (e.g. day-of-week effects, test backlogs). Modelled as $\text{NegBin}(\rho \Delta R, \phi)$.

Observation Model: Negative-Binomial reporting

$$\mathbf{y}_k \sim \text{NegBin}(\mu_k = \rho \cdot \Delta R_k, \phi)$$

ρ — reporting probability ·

ϕ — overdispersion ($\phi \rightarrow \infty$ gives Poisson)

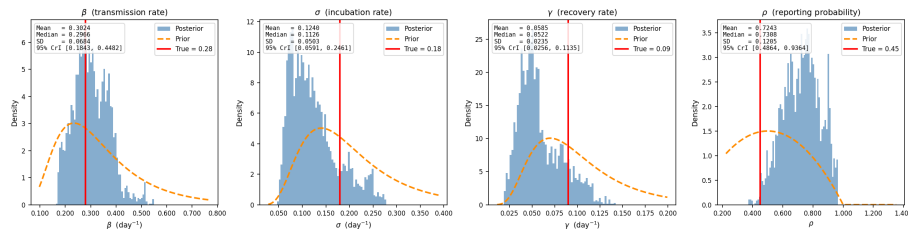
Fit to data via particle MCMC

① Estimate likelihood with bootstrap particle filter

② Update parameters in via standard M-H MCMC

Can estimate parameters

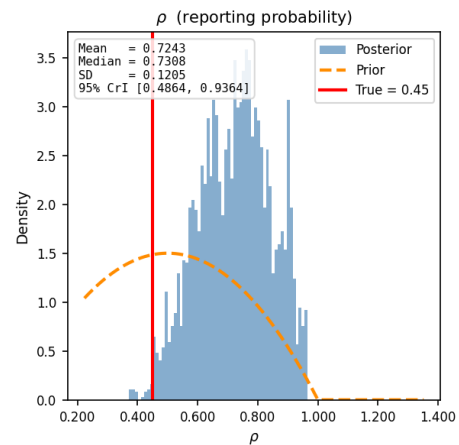
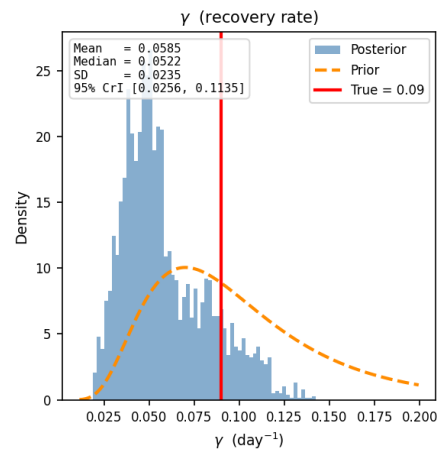
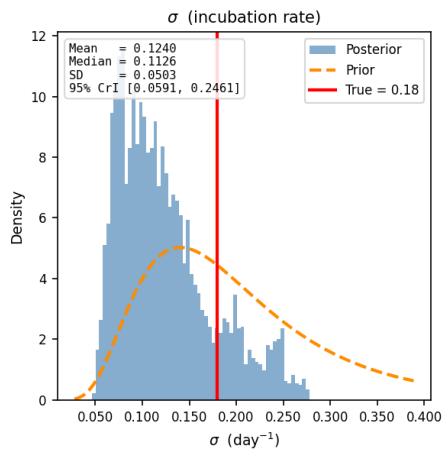
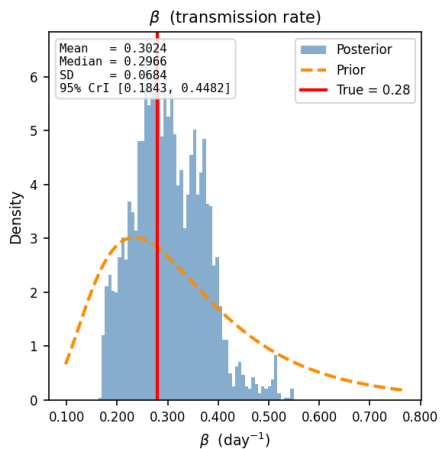
Posterior distributions of SEIR parameters (post burn-in MCMC samples)



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Synthetic SDE trajectories → reported cases via Negative-Binomial

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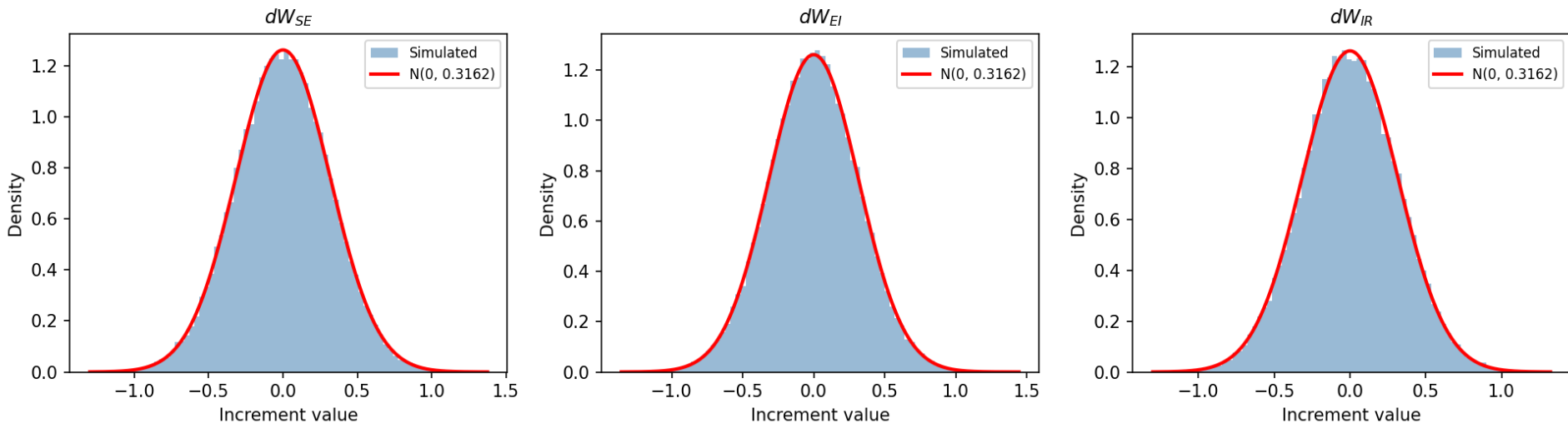
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Brownian increments are Latent residuals in this context

Once model is fitted to data do increments vary from expectation?

Brownian increment distributions [expected $N(0, \text{sqrt}(dt))$, $\text{sqrt}(dt) = 0.3162$]



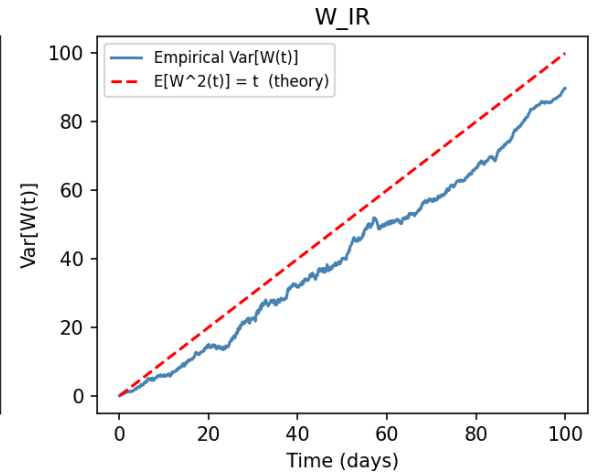
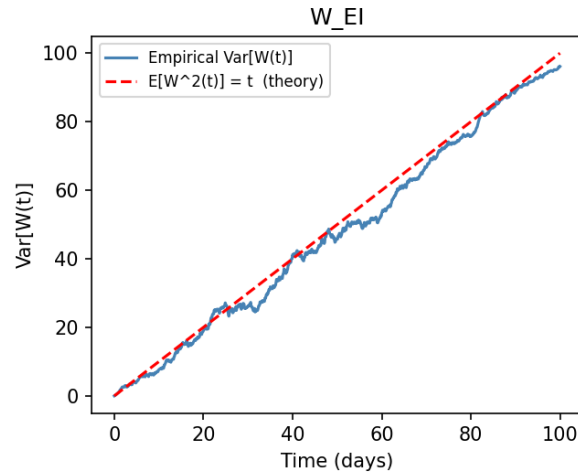
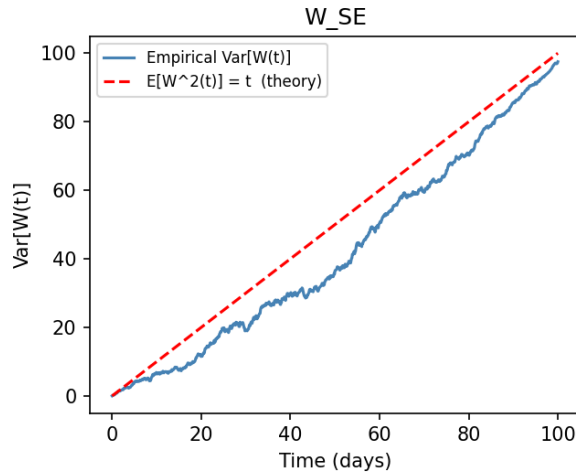
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Variance of $W(t)$ across particles [should equal t]



Model mismatch – SEIR fitted to data generated by SIR model

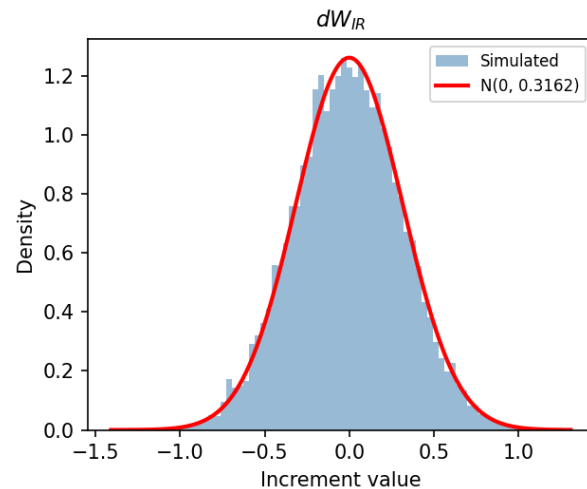
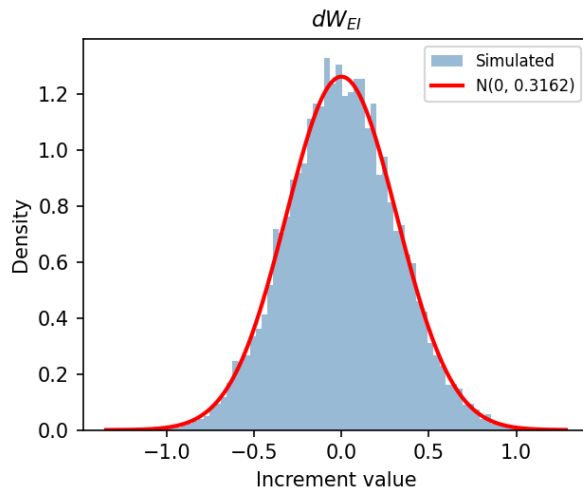
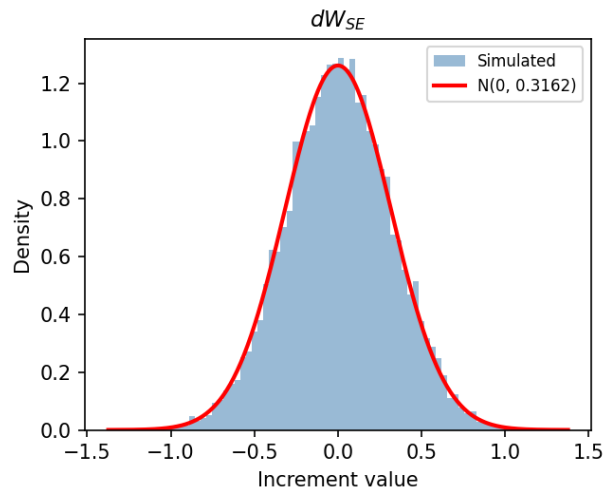
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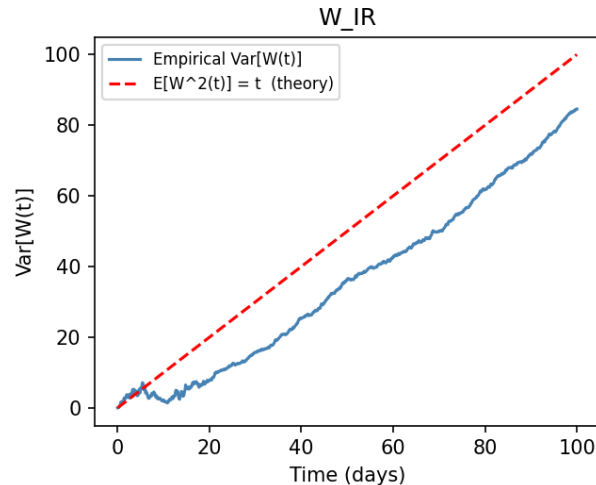
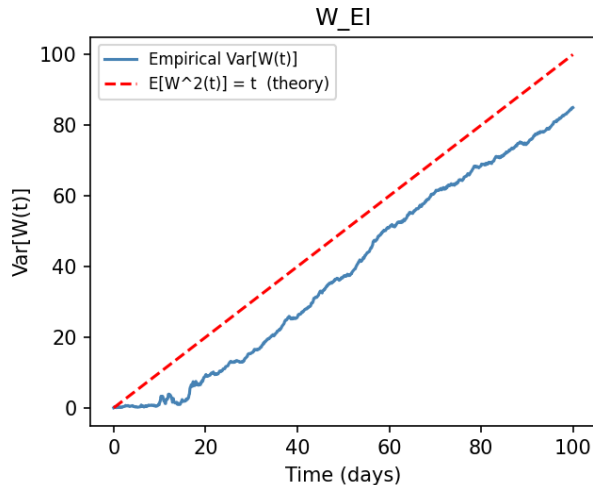
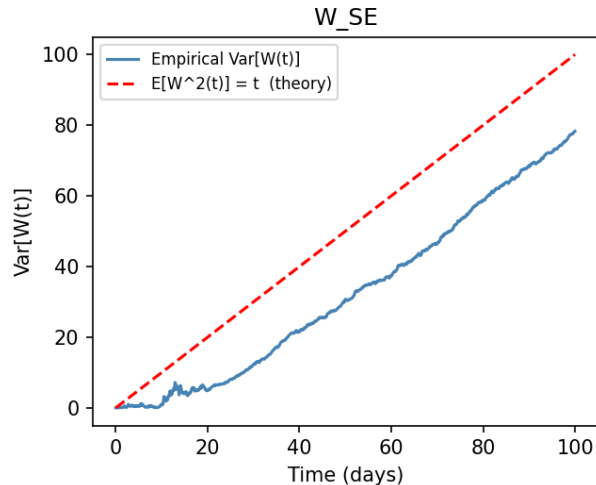
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Suggests mismatch early on in epidemic ... perhaps indicative of lack of E state?

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What tools and results are available for complex noise terms

Modelling heterogeneity

What tools & results carry over to heterogeneous systems

Spatial models

Spatial dynamics and spread – how can we use SDEs/PDEs

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